

Multilevel Processor Sharing Scheduling Disciplines: Mean Delay Analysis

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1

Background

- File transfers in the Internet use TCP
 - a file is splitted into packets which are sent (in a controlled way) from the source node to the destination node
 - flow = packets related to a file
 - due to the congestion control part of TCP, the network resources are shared fairly (in the ideal case)
- Internet measurements show that
 - a small number of large TCP flows responsible for the largest amount of data transferred (elephants)
 - most of the TCP flows made of few packets (mice)
- Intuition says that
 - favoring short flows reduces the total number of flows, and thus, by Little's law, also the mean "file transfer" time

Mathematical model

- Consider a bottleneck link loaded with elastic flows
 - such as file transfers using TCP
- Assume that
 - the flows arrive according to a Poisson process with rate λ
 - each flow has a random service requirement (= file size) with a general distribution with mean L
 - cumulative distribution function F(x), tail distribution function G(x) = 1 F(x), density f(x), hazard rate h(x) = f(x) / G(x)
 - typically heavy-tailed such as **Pareto** ⇒ decreasing hazard rate
- So, at the flow level, we have a **M/G/1** queueing system
 - customers = flows = file transfers (not individual packets!)
 - delay = file transfer time
 - service time = file size / link capacity C
 - service rate = μ = link capacity *C* / mean file size *L*
 - load = ρ = λ / μ

Scheduling disciplines

- **PS** = Processor Sharing
 - Without any specific scheduling policy, the flows are assumed to divide the bottleneck link capacity evenly (= fairness in the ideal case)
- **SRPT** = Shortest Remaining Processing Time
 - Choose a packet of the flow with least packets left
- LAS = Least Attained Service
 - Choose a packet of the flow with least packets sent
 - Also called: **FB** = Foreground-Background
- **MLPS** = Multilevel PS (cf. Kleinrock (1976))
 - Choose a packet of the flow with less packets sent than a given threshold
- Notes:
 - All of them are **work-conserving** disciplines
 - Only SRPT uses "future" information

Optimality results for M/G/1

- If the remaining service times (= number of packets left) are known for each customer (= flow), then
 - Schrage (1968):
 SRPT optimal minimizing the mean delay (= file transfer time)
- If only the attained service times (= number of packets sent) are known for each customer (= flow), then
 - Yashkov (1978):
 Decreasing hazard rate ⇒
 FB optimal among work-conserving scheduling disciplines
 - Feng and Misra (2003):
 the same result as above proved (?) in another way
 - Wierman et al. (2002):
 Decreasing hazard rate ⇒ FB better than PS

MLPS scheduling disciplines

- Definition:
 - Based on the attained service times
 - Thresholds $0 = a_0 < a_1 < \ldots < a_N < a_{N+1} = \infty$ define N+1 levels, with a strict priority between the levels
 - Within a level, either FB or PS is applied
- **Example**: Two levels with threshold *a*
 - FB+FB = FB = LAS
 - FB+PS = FLIPS (Feng and Misra (2003))
 - PS+PS = ML-PRIO (Guo and Matta (2002))

Conditional mean delay formulas for M/G/1

- Notation: T(s) = delay of a customer with service time s
- PS:

$$E[T(s)] = \frac{s}{1-\rho}$$

• FB:

$$E[T(s)] = \frac{E[W_s] + s}{1 - \rho_s}$$

• **PS+PS**(*a*):

$$E[T(s)] = \begin{cases} \frac{s}{1-\rho_a}, & s \le a\\ \frac{E[W_a]+a}{1-\rho_a} + \frac{\alpha(s-a)}{1-\rho_a}, & s > a \end{cases}$$

Related queueing systems

• M/G/1 with truncated service times $\min\{S,x\}$:

$$\rho_x = \lambda E[\min\{S, x\}]$$
$$E[W_x] = \frac{\lambda E[(\min\{S, x\})^2]}{2(1 - \rho_x)}$$

• $M^X/G/1$ -PS with modified service times S:

$$P\{\widetilde{S} \le x\} = P\{S \le a + x \mid S > a\}$$

$$\alpha(x) = E[\widetilde{T}(x)] \text{ satisfying}$$

$$\alpha'(x) = \frac{\lambda}{1 - \rho_a} \int_0^x \alpha'(y) G(a + x - y) dy$$

$$+ \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + c(x) + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) G(a + x - y) dy + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y) dy + \frac{\lambda}{1 - \rho_a} \int_0^\infty \alpha'(y)$$

Conditional mean delay E[T(s)]



Note: exponential service time distribution

Asymptotic properties of the conditional mean delay E[T(s)]



• Conclusion: PS+PS seems to be better than FB in the asymptotic region (when hazard rate decreasing)

Mean delay E[T]



 Conclusion: PS+PS seems to be better than PS in the mean delay sense (when hazard rate decreasing)

Problem

• Theorem: With decreasing hazard rate,

$$E[T^{\text{FB}}] \le E[T^{\text{FB}+\text{PS}}] \le E[T^{\text{PS}+\text{PS}}] \le E[T^{\text{PS}}]$$

- Steps in the proof:
 - **First**: prove that for any work-conserving disciplines D_1 and D_2

$$E[U_x^{D_1}] \le E[U_x^{D_2}] \quad \forall x \quad \Rightarrow \quad E[T^{D_1}] \le E[T^{D_2}]$$

• T = delay

- U_x = unfinished truncated work = sum of remaining truncated service times min{S,x} of those customers who have attained service at most x time units
- **Second**: prove that for any *x*

$$E[U_x^{\text{FB}}] \le E[U_x^{\text{FB}+\text{PS}}] \le E[U_x^{\text{PS}+\text{PS}}] \le E[U_x^{\text{PS}}]$$

Solution: mean value arguments (1)

• Proposition 1: If no "future" information used, then

$$E[T] = \frac{1}{\lambda} \int_{0}^{\infty} (E[U_x])' h(x) dx$$

- Proof:
 - Kleinrock (1976) by Little's formula:

$$dE[N(y)] = \lambda G(y) dE[T(y)]$$

- *N*(*y*) = #customers with attained service time at most *y*
- *T*(*y*) = delay of a customer with service time *y*
- Easy to see:

$$E[R_x(y)] = \frac{1}{G(y)} \int_y^x G(t) dt$$

- R_x(y) = min{S(y),x} min{y,x} = remaining truncated service time of a customer with attained service time y
- S(y) = service time of a customer with attained service time y^{-13}

Solution: mean value arguments (2)

- No "future" information used:

$$E[U_x] = \int_{0^-}^{x} E[R_x(y)] dE[N(y)]$$

• U_x = unfinished truncated work:

$$U_x = \sum_i (\min\{S_i, x\} - \min\{X_i, x\})$$

- S_i = service time of customer *i*
- X_i = attained service time of customer *i*
- By combining the results above, we finally get

$$(E[U_x])' = \lambda G(x) E[T(x)]$$

implying that

$$E[T] = \int_{0}^{\infty} E[T(x)]f(x)dx = \frac{1}{\lambda} \int_{0}^{\infty} (E[U_x])'h(x)dx$$

Solution: mean value arguments (3)

• Proposition 2: With decreasing hazard rate,

 $E[U_x^{D_1}] \le E[U_x^{D_2}] \quad \forall x \implies E[T^{D_1}] \le E[T^{D_2}]$

- Proof:
 - Follows directly from Proposition 1.
 - If the hazard rate differentiable, then simply by partial integration:

$$E[T^{D_1}] - E[T^{D_2}] = \frac{1}{\lambda} \int_{0}^{\infty} (E[U_x^{D_1}] - E[U_x^{D_2}])'h(x)dx$$
$$= -\frac{1}{\lambda} \int_{0}^{\infty} (E[U_x^{D_1}] - E[U_x^{D_2}])h'(x)dx$$

Solution: mean value arguments (4)

• **Proposition 3**: For any *a* and *x*,

$E[U_x^{\text{PS+PS}(a)}] \le E[U_x^{\text{PS}}]$

- Proof:
 - From slide 7:

$$E[T^{\text{PS+PS}}(s)] = \begin{cases} \frac{s}{1-\rho_a} \le \frac{s}{1-\rho} = E[T^{\text{PS}}(s)], & s \le a \\ \\ E[T^{\text{FB}}(a)] + \frac{\alpha(s-a)}{1-\rho_a}, & s > a \end{cases}$$

- Notation:

$$\alpha^* = \inf_{x>0} \alpha'(x)$$

- From slide 8:

$$\inf_{s>a} (T^{PS+PS}(s))' = \frac{\alpha^*}{1-\rho_a} \ge \frac{1}{1-\rho} = (T^{PS}(s))$$

16

Solution: mean value arguments (5)

– Notation:

$$x^* = \inf\{s \ge a \mid E[T^{PS+PS}(s)] \ge E[T^{PS}(s)]\}$$

- For all $x \leq x^*$,

$$E[U_x^{\text{PS+PS}}] = \int_0^x \lambda G(s) E[T^{\text{PS+PS}}(s)] ds$$
$$\leq \int_0^x \lambda G(s) E[T^{\text{PS}}(s)] ds = E[U_x^{\text{PS}}] ds$$

- For all $x > x^*$,

$$(E[U_x^{\text{PS+PS}}])' = \lambda G(x) E[T^{\text{PS+PS}}(x)]$$

$$\geq \lambda G(x) E[T^{\text{PS}}(x)] = (E[U_x^{\text{PS}}])'$$

- Finally, since both PS and PS+PS are work-conserving, we have $E[U_{\infty}^{\rm PS+PS}] = E[U_{\infty}^{\rm PS}]$

Solution: sample path arguments (1)

• **Notation**: unfinished truncated work for discipline *D* at time *t*:

$$U_x^D(t) = \sum_{i=1}^{A(t)} (\min\{S_i, x\} - \min\{X_i(t), x\})$$

$$= \sum_{i=1}^{A(t)} \min\{S_i, x\} - \int_0^t \sigma_x^D(u) du$$

- A(t) = #arrivals up to time t
- X_i = service time of customer *i*
- $X_i(t)$ = attained service time of customer *i* at time *t*
- $\sigma_x^{D}(t)$ = service rate of customers with attained service less than *x* at time *t*
- For any scheduling discipline *D*,

$$\sigma_x^D(t) = 0, \quad \text{if } N_x^D(t) = 0$$

$$\sigma_x^D(t) \le 1, \quad \text{if } N_x^D(t) > 0$$

- $N_x^D(t)$ = #customers with attained service less than x at time t

18

Solution: sample path arguments (2)

• **Definition**: set D_x^* of scheduling disciplines:

$$D \in D_x^* \iff \sigma_x^D(t) = 1, \text{ if } N_x^D(t) > 0$$

• By definition, for any D^* in D_x^* , x, t,

$$U_x^{D^*}(t) = \min_D U_x^D(t)$$

• **Proposition 4**: For any *a*, *x*, *t*,

$$U_x^{\text{FB}}(t) \le U_x^{\text{FB+PS}(a)}(t) \le U_x^{\text{PS+PS}(a)}(t)$$

- Proof:
 - Clearly, for all x and $a \ge x$,

$$FB, FB + PS(a) \in D_{\chi}^{*}$$

- On the other hand, for all $a \le x$,

$$\sigma_x^{\text{FB+PS}(a)}(t) \equiv \sigma_x^{\text{PS+PS}(a)}(t)$$
¹⁹

Solution: sample path arguments (3)

• Give an example of *x* and *t* such that

$$U_x^{\mathrm{PS+PS}}(t) > U_x^{\mathrm{PS}}(t)$$

• Not so easy. But it is another story ...

